



## Website & Projects

## PASQUALE BUONOCORE

### Mechatronics Engineer

Salerno/Italia | +39 339 80 89 373

pasquale.buonocore@hotmail.it

 [Github](#)

 [Linkedin](#)

 [Youtube](#)

 [Website](#)

## WHO AM I?

I am a Mechatronics engineer (based in Florence) currently working as an Embedded Software Engineer for Particle Measuring Systems, a multinational company based in Boulder, CO. Hard work, perseverance, stepping out of my comfort zone, and critical thinking are my main tools for dealing with deadlines and heavy pressure. Working and studying in international environments has allowed me to collaborate on and develop projects with Italian and non-Italian engineers in groups and independently. My main interests include embedded systems, robotics, industrial automation, and software development.

## EXPERIENCE

### PARTICLE MEASURING SYSTEM, FRASCATI

06/2023 - now

EMBEDDED SOFTWARE DEVELOPER

I am currently developing embedded software for an Embedded Linux platform within the R&D group, primarily using Rust and C++ programming languages. My work involves gaining valuable experience in areas such as the Yocto Project, Linux driver implementation, and OS management.

Tools: C++, Rust, Linux, Yocto, Jenkins, Confluence, Jira, Jama, Zync Board

### ITALSYSTEM SRL, AVELLINO

09/2020 - 06/2023

MODEL-BASED DESIGN AND TEST ENGINEER FOR EMBEDDED SYSTEMS

Consulting experiences for both production and research projects. My main project involves the development of embedded software for a convertible airplane, following a Model-Based Development (MBD) approach. I have gained extensive experience in both software simulation and hardware testing for this project.

Tools: Matlab, Simulink, Stateflow, Python, C/C++, Linux, CCS, DOORS.

Normative: DO178C, DO331, MISCRA C, MAAB

### ITALIAN INSTITUTE OF TECHNOLOGY, GENOVA

09/2019 - 03/2020

MASTER'S THESIS RESEARCH: *A MODEL PREDICTIVE CONTROL APPROACH FOR FATIGUE AWARE ROBOTIC HEAVY MANIPULATION*

The research addresses motors protection from overheating when the robot handles heavy objects through an optimal control approach.

Tools: Matlab, Python, C++, Linux, ROS

## EDUCATION

### UNIVERSITY OF TRENTO

2017-2020

M.S IN MECHATRONICS ENGINEERING - ROBOTICS AND ELECTRONICS 110/110

### UNIVERSITY OF SALERNO

2013-2017

B.S IN MECHANICAL ENGINEERING 110/110 CUM LAUDE

### ITIS BASILIO FOCACCIA

2008-2013

HIGH SCHOOL ELECTRICAL ENGINEER, 100/100

## SKILLS

<b>PROGRAMMING LANGUAGES</b>	Python   C   C++   Matlab   Rust
<b>MODELLING &amp; SIMULATION</b>	Maple   Simulink   Stateflow   SolidWorks   Cura3D   Psim   Altium
<b>FRAMEWORKS &amp; LIBRARIES</b>	Jupyter   Matplotlib   Numpy   OpenCV   kivy   ROS
<b>EMBEDDED SYSTEMS</b>	Arduino   Raspberry Pi   Pic   Beaglebone   Texas F2837   Zync Zc602
<b>PROJECT MANAGEMENT</b>	DOORS   Jama   Confluence   Jira   BitBucket   Git
<b>SPARE TIME</b>	App development   Web 3   Stampa 3D   Drone and robots
<b>LANGUAGES</b>	<b>Native:</b> Italian <b>Fluent:</b> English <b>Interested in:</b> German/French